



DIPLOMA WING

# **RAJIV GANDHI PROUDYOGIKI VISHWAVIDYALAYA, BHOPAL**

SCHEME OF STUDIES & EXAMINATIONS ( IMPLEMENTED FROM SESSION : JULY 2023)

SCHEME
OCBC JULY 2022/2023

NAME OF BRANCH
ET & TELECOMMUNICATION

BRANCH CODE
E03

SEMESTER
SIXTH (VI)

S.N.	PAPER CODE	SUBJECT CODE	SUBJECT NAME	THEORY COMPONENT							PRACTICAL COMPONENT					TOTAL CREDITS	TOTAL MARKS	
				HRS PER WEEK	CREDITS	TERM WORK			THEORY PAPER		HRS PER WEEK	CREDITS	LAB WORK	PRACTICAL EXAM/VIVA				
						QUIZ/ASSIGNMENT	MID TERM TEST*		TOTAL	MARKS				DURATION	MARKS			DURATION
							I	II										
1	7386	601	ENTREPRENEURSHIP & START-UPS	4	4	10	10	10	30	70	03 Hrs.	0	0	0	0	0	4	100
2	7472	602	COMPU. NET. & DATA COMM.	7	7	10	10	10	30	70	03 Hrs.	6	3	20	30	3 Hrs.	10	150
3	7605	611	ARTIFICIAL INTELLIGENCE OR	3	3	10	10	10	30	70	03 Hrs.	0	0	0	0	0	3	100
	7607	612	PRODUCT DESIGN															
4	7609	621	MECHATRONICS OR	3	3	10	10	10	30	70	03 Hrs.	0	0	0	0	0	3	100
	7611	622	INDUSTRIAL ROBOTS															
5			INDIAN CONSTITUTION	2	0	0	0	0	0	0	0	0	0	0	0	0	0	0
6			MAJOR PROJECT **	0	0	0	0	0	0	0	0	6	4	100	50	03 Hrs.	4	150
7			SEMINAR ***	3	1	50	0	0	50	0	0	0	0	0	0	0	1	50
8			LIBRARY/VISITS etc.	0	0	0	0	0	0	0	0	2	0	0	0	0	0	0
TOTAL				22	18				170	280		14	7	120	80		25	650

- NOTE -**
- (1)\* Two Best, out of Three Mid Term Tests (Progressive Tests) Marks should be entered here.
  - (2)\*\* One Credit is carried forward from the Vth semester major project evaluation.
  - (3)\*\*\* One Hour Time duration for each student.

GRAND TOTAL OF CREDITS
25

GRAND TOTAL OF MARKS
650



DIPLOMA WING

# RAJIV GANDHI PROUDYOGIKI VISHWA VIDYALAYA, BHOPAL

SCHEME
OCBC JULY 2022/2023

NAME OF BRANCH AND BRANCH CODE
ELECTRONICS AND TELECOMMUNICATION-E03
ELECTRONICS ENGINEERING-E06

SEMESTER
SIXTH(VI)

SCHEME OF STUDIES & EXAMINATIONS (IMPLEMENTED FROM SESSION: JULY 2023)

S.N.	PAPER CODE	SUBJECT CODE	SUBJECT NAME	THEORY COMPONENT							PRACTICAL COMPONENT					TOTAL CREDITS	TOTAL MARKS	
				HRS PER WEEK	CREDITS	TERM WORK			THEORY PAPER		HRS PER WEEK	CREDITS	LABWORK	PRACTICAL EXAM/VIVA				
						QUIZ/ASSIGNMENT	MID TERM TEST*		TOTAL	MARKS				DURATION	MARKS			DURATION
							I	II										
1	7386	601	ENTREPRENEURSHIP AND START-UPS	4	4	10	10	10	30	70	03Hrs.	0	0	0	0	0	4	100
2	7472	602	COMPUTER NETWORKING AND DATA COMMUNICATION	7	7	10	10	10	30	70	03Hrs.	6	3	20	30	3Hrs.	10	150
3	7605	611	ARTIFICIAL INTELLIGENCE OR	3	3	10	10	10	30	70	03Hrs.	0	0	0	0	0	3	100
	7607	612	PRODUCT DESIGN															
4	7609	621	MECHATRONICS OR	3	3	10	10	10	30	70	03Hrs.	0	0	0	0	0	3	100
	7611	622	INDUSTRIAL ROBOTS															
5			INDIAN CONSTITUTION	2	0	0	0	0	0	0	0	0	0	0	0	0	0	0
6			MAJOR PROJECT**	0	0	0	0	0	0	0	0	6	4	100	50	03Hrs.	4	150
7			SEMINAR***	3	1	50	0	0	50	0	0	0	0	0	0	0	1	50
8			LIBRARY/VISITS etc.	0	0	0	0	0	0	0	0	2	0	0	0	0	0	0
TOTAL				22	18				170	280		14	7	120	80		25	650

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GRAND TOTAL OF MARKS
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DIPLOMA WING

RAJIV GANDHI PROUDYOGIKI VISHWAVIDYALAYA, BHOPAL

**DIPLOMA IN ET. & TELECOMMUNICATION ENGINEERING (E03)**

**SEMESTER VI**

COURSE TITLE	ENTREPRENEURSHIP AND START-UPS
PAPER CODE	7386
SUBJECT CODE	601
THEORY CREDITS	04
PRACTICAL CREDITS	00

**Course Learning Objectives:**

1. Acquiring Entrepreneurial spirit and resourcefulness.
2. Familiarization with various uses of human resource for earning dignified means of living.
3. Understanding the concept and process of entrepreneurship - its contribution and role in the growth and development of individual and the nation.
4. Acquiring entrepreneurial quality, competency, and motivation.
5. Learning the process and skills of creation and management of entrepreneurial venture.

**Course Content:**

S. No.	Unit	Topic	Sub – Topic	Hours	Marks
1.	Unit 1	Introduction to Entrepreneurship and Start-Ups	<ul style="list-style-type: none"><li>• Entrepreneurship concept, need of entrepreneurs, traits of entrepreneur, function of entrepreneur, motivation, types of motivation, Maslow's need hierarchy</li><li>• Concept of start-up, key aspects, start-up India, why entrepreneurs fail, intrapreneur,</li></ul>	12	12

			<p>similarities/differences between intrapreneur, entrepreneur, businessman and manager.</p> <ul style="list-style-type: none"> <li>Types of business structures: Sole proprietor, one person company, partnership, LLP, private limited company, public limited company, non-profit organizations (trusts, societies, section 8 companies), government sector companies.</li> </ul>		
2.	Unit 2	Business ideas and their implementation	<ul style="list-style-type: none"> <li>Business ideas, sources of business ideas, techniques to discover business ideas.</li> <li>Visualizing business ideas: Define business idea, utilize visual tools and techniques to refine business idea (business model canvas, mind mapping, story boarding, infographics)</li> <li>Feasibility of business ideas: technical, operational, financial, marketing, environmental</li> <li>Steps to frame business plan</li> <li>Activity map: concept, objective, use</li> </ul>	10	12

3.	Unit 3	Idea to start up	<ul style="list-style-type: none"> <li>• Market analysis- identifying the target market (target market segmentation, customer profiling, estimating market size, customer need analysis)</li> <li>• Competition evaluation and strategy development: identifying competitors, strategies for handling competition</li> <li>• Marketing: 4 P's of marketing (Product, Price, Place, and Promotion), developing a marketing plan, marketing strategies</li> <li>• Accounting: Basic terminologies – Debit, Credit, Capital, Assets, Liabilities, Profit, Loss, Balance sheet, Cash Flow, Return on Investment, gross margin, break-even analysis</li> <li>• Risk analysis: type of risks (financial, market, regulatory and compliance, operational, economic).</li> </ul>	10	12
4.	Unit 4	Management	<ul style="list-style-type: none"> <li>• Company's organization Structure: objective, key aspects, types of organization structure</li> <li>• Recruitment and management of talent: importance of recruitment, job description, recruitment methods, key aspects and importance of talent management</li> <li>• Financial organization and management: Elements of financial management, objective of financial management (Profit maximization, Wealth maximization)</li> </ul>	10	12

5.	Unit 5	Financing and Protection of Ideas	<ul style="list-style-type: none"> <li>Financing methods available for start-ups in India: Bootstrapping, Angel investors, Friends and family, Venture capital, corporate venturing, Crowdfunding, Government grants and loans, Bank loans and microfinance, incubators and accelerators, IPO.</li> <li>Communication of Ideas to potential investors: Investor Pitch, Investor pitch steps</li> <li>Patenting and Licenses: Trademark, benefits of trademark, IPR, IPR Contracts</li> </ul>	10	12
6.	Unit 6	Exit strategies for entrepreneurs, bankruptcy, and succession and harvesting strategy	<ul style="list-style-type: none"> <li>Reasons for entrepreneurial exits</li> <li>Types of exit strategies: Acquisition, Merger, Management Buyout, Liquidation.</li> <li>Bankruptcy: concept and Impact on stakeholders</li> <li>Bankruptcy Alternatives methods: debt restructuring, operational restructuring, strategic partnerships</li> </ul>	08	10

Suggested Case Studies:

- Case study on any business idea
- Case study of balance sheet

Learning Outcome:

Upon completion of the course, the student will be able to demonstrate knowledge of the following topics:

1. Understanding the dynamic role of entrepreneurship and small businesses
2. Organizing and Managing a Small Business
3. Financial Planning and Control
4. Forms of Ownership for Small Business
5. Strategic Marketing Planning
6. New Product or Service Development
7. Business Plan Creation

**SUGGESTED LEARNING RESOURCES:**

S. No.	Title of Book	Author	Publication
1	The Startup Owner's Manual: The Step-by-Step Guide for Building a Great Company	Steve Blank and Bob Dorf	K & S Ranch ISBN – 978-0984999392
2	The Lean Startup: How Today's Entrepreneurs Use Continuous Innovation to Create Radically Successful Businesses	Eric Ries	Penguin UK ISBN – 978-0670921607
3	Demand: Creating What People Love Before They Know They Want It	Adrian J. Slywotzky with Karl Weber	Headline Book Publishing ISBN – 978-0755388974
4	The Innovator's Dilemma: The Revolutionary Book That Will Change the Way You Do Business	Clayton M. Christensen	Harvard business ISBN: 978-142219602

**SUGGESTED SOFTWARE/LEARNING WEBSITES:**

- a. <https://www.fundable.com/learn/resources/guides/startup>
- b. <https://corporatefinanceinstitute.com/resources/knowledge/finance/corporatestructure/>
- c. <https://www.finder.com/small-business-finance-tips>
- d. <https://www.profitbooks.net/funding-options-to-raise-startup-capital-for-your-business/>

DIPLOMA WING

RAJIV GANDHI PROUDYOGIKI VISHWAVIDYALAYA, BHOPAL

DIPLOMA IN ET. & TELECOMMUNICATION ENGINEERING (E03)

SEMESTER VI

COURSE TITLE	Artificial Intelligence
PAPER CODE	7605
SUBJECT CODE	611
TREORY CREDITS	03
PRACTICAL CREDITS	00

**Course Objectives:** After completing this course, students will be able to, understand the fundamental concepts, goals, applications, and benefits of Artificial Intelligence.

**Course Content:**

S. No.	Unit	Topic	Sub – Topic	Hours	Marks
1.	Unit 1	Introduction to Artificial Intelligence	Introduction to Artificial Intelligence • Artificial Intelligence (AI) definition • Goals of AI • Applications of AI • Benefits of AI	09	15



2.	Unit 2	Agents and Environments	<p>Key Components of AI system</p> <ul style="list-style-type: none"> <li>• Overview of interaction between Agents and Environment</li> <li>• Working of AI agents <ul style="list-style-type: none"> <li>- Collecting Information (Perceiving the Environment)</li> <li>- Processing Information &amp; Making Decisions</li> <li>- Taking Action (Performing Tasks)</li> <li>- Learning &amp; Improving Over Time</li> </ul> </li> </ul> <p>Structure of an AI Agent:</p> <ul style="list-style-type: none"> <li>• Architecture</li> <li>• Agent Program</li> </ul> <p>Goals of Agents</p> <p>Types of Agents – <b>(Definition, Block diagram &amp; Application)</b></p> <ul style="list-style-type: none"> <li>• Simple Reflex Agents,</li> <li>• Model Based Reflex Agents</li> <li>• Goal Based Agents</li> <li>• Utility based agents</li> <li>• Learning agents</li> <li>• Multi- agent systems</li> <li>• Hierarchical agents</li> </ul> <p>Types of Environments <b>(Definitions with examples only)</b></p> <ul style="list-style-type: none"> <li>• Fully Observable vs Partially Observable</li> <li>• Deterministic vs Stochastic</li> <li>• Competitive vs Collaborative</li> <li>• Single-agent vs Multi-agent</li> <li>• Static vs Dynamic</li> <li>• Discrete vs Continuous</li> <li>• Episodic vs Sequential</li> <li>• Known vs Unknown</li> </ul>	09	15
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3.	Unit 3	Search Algorithms in AI	<p>Terminology used in Search Problem(<b>Definition only</b>)</p> <ul style="list-style-type: none"> <li>• State space,</li> <li>• Start State,</li> <li>• Goal State,</li> <li>• Solution and Plan</li> </ul> <p>Types of Search Algorithms (<b>Concept using Tree &amp; Graph methods</b>)</p> <p>1. Brute Force Search</p> <ul style="list-style-type: none"> <li>• Depth First Search</li> <li>• Breadth First search</li> </ul> <p>2. Heuristic Search</p> <ul style="list-style-type: none"> <li>• Greedy Search</li> <li>• A* Tree Search</li> <li>• A* Graph Search</li> </ul>	09	10
4.	Unit 4	Fuzzy Logic Systems	<p>Introduction to Fuzzy Logic and Fuzzy systems in AI</p> <p>Difference between Boolean Logic and Fuzzy Logic</p> <p>Definition of Fuzzification &amp; Defuzzification, Membership functions (Triangular &amp; Trapezoidal)</p> <p>Advantages, Disadvantages and Applications of Fuzzy Logic Systems</p>	09	15
5.	Unit 5	Artificial Neural Networks (ANN)	<p>Introduction to Artificial Neural Networks (ANN)</p> <p>Neural Networks Architecture (Overview of Input layer, Hidden layer, Output layer)</p> <p>Comparison between Artificial neurons vs Biological neurons</p> <p>Learning Technique: Overview of Back-propagation in ANN</p> <p>Difference between Deep Learning &amp; Machine Learning</p>	09	15

**Reference Books:**

<b>S. No.</b>	<b>Title of Book</b>	<b>Author</b>	<b>Publication</b>
1	Artificial Intelligence by examples: Develop machine Intelligence from scratch using real artificial intelligence use cases	Denis Rothman	Packt Publishing ISBN – 978- 1788990547

**DIPLOMA WING**

**RAJIV GANDHI PROUDYOGIKI VISHWAVIDYALAYA, BHOPAL**

**DIPLOMA IN ELECTRONICS & TELECOMMUNICATION ENGINEERING (E03)**

**SEMESTER V**

COURSE TITLE	:	Product Design
PAPER CODE	:	7607
SUBJECT CODE	:	612
TREORY CREDITS	:	03
PRACTICAL CREDITS	:	00

**Course Objective:**

To equip students with a foundational understanding of product development principles, including classification and the new product development (NPD) process, fostering creativity and innovation. To develop skills in analyzing product life cycles, understanding optimized solutions, and applying modern tools like Six Sigma for market-ready product design.

**Course Content:**

Unit	Topics and Sub-topics	Hours	Marks
<b>Unit-1</b> <b>Fundament als of product design</b>	<b>Product:</b> Definition, characteristics, classification and differentiation. Types of products, Levels of product, Product-market mix. <b>New product development process:</b> <ul style="list-style-type: none"><li>• Characteristics of successful Product development</li><li>• Stages of new product development.</li><li>• Idea generation methods: creativity, brain storming, mind mapping, screening.</li><li>• challenges of new Product development.</li></ul>	<b>9</b>	<b>14</b>
<b>Unit 2 –</b> <b>Product life cycle</b>	<b>Product life cycle:</b> Concept of product life cycle (PLC), benefits and drawbacks of using the Product Life Cycle, various stages in the product life cycle. <b>PLC as a tool for:</b> planning, marketing strategy etc. <b>Product analysis:</b> Economic considerations, Production and Marketing aspects, Customer need identification. Product development practices and industry-product strategies.	<b>9</b>	<b>14</b>

<b>Unit 3- Product design approaches</b>	<p><b>Product design:</b> design by evolution, design by innovation, design by imitation.</p> <ul style="list-style-type: none"> <li>• The three S's of design: standardization, simplification, and specialization ,</li> <li>• Effect of simplification on Pareto diagram (ABC diagram).</li> </ul> <p><b>Modern approach to product design :</b> concurrent design and quality function deployment</p> <p><b>Factors affecting product design:</b> technical, industrial, environmental, aesthetics, standards of performance.</p>	<b>9</b>	<b>14</b>
<b>Unit 4- Optimization in Product design</b>	<p><b>Introduction to optimization in design</b>(concept only): objective function, design variables, constraints design space, difference between feasible design , Infeasible design</p> <p><b>Economic factors in design-</b> financial feasibility: concept of Cost-benefit analysis, Return on investment (ROI), Pricing model, Market demand, Risk assessment.</p> <p><b>Design for safety and reliability.</b></p> <p><b>Role of computers in design-</b> Modeling and Simulation, The role of models in engineering design.</p> <p><b>Design for manufacturing (DFM)-</b>Rapid Prototyping (RP) types of RP and applications in product design, Advantages &amp; disadvantages of Rapid Prototyping.</p> <p><b>Modern design practices:</b> Concurrent design- Six Sigma Difference between Product development and product design.</p>	<b>9</b>	<b>14</b>
<b>Unit-V Design of simple products</b>	<p>Design of simple products considering all aspects of product development.</p> <p><b>Complete design cycle</b> for example chair, water bottle, pen, mobile app etc. From need identification to final manufacturing/development.</p>	<b>9</b>	<b>14</b>

#### SUGGESTED LEARNING RESOURCES:

##### Reference Books:

1. Product Design and Manufacturing, Chitale A K and Gupta R C, Prentice Hall of India, 2005.
2. Product Design and Development, Karl T. Ulrich and Steven D. Eppinger, Tata McGraw– Hill edition.
3. Product innovation & Entrepreneurship Vigneswaran Chidambaram, e-Kumbh AICTE,
4. Product and Brand management e-KUMBH AICTE, ignou THE PEOPLE'S UNIVERSITY
5. Engineering Design –George E. Dieter.
6. An Introduction to Engineering Design methods Vijay Gupta.
7. Merie Crawford : New Product management, McGraw-Hill Irwin.
8. Product Design, Kevin Otto and Kristin Wood, Techniques in Reverse Engineering and New Product Development, Pearson education.

##### Course outcomes:

At the end of the course, the student will be able to:

CO1 Understand the basic concepts of product design and development process.

CO2 Illustrate the methods to define the customer needs.

CO3 Describe an engineering design and development process.

CO4 Understand the intuitive and advanced methods used to develop and evaluate a concept.

CO5 Apply modeling and embodiment principles in product design and development process

**DIPLOMA WING****RAJIV GANDHI PROUDYOGIKI VISHWAVIDYALAYA, BHOPAL****DIPLOMA IN ELECTRONICS & TELECOMMUNICATION ENGINEERING (E03)****SEMESTER V**

COURSE TITLE	:	Mechatronics
PAPER CODE	:	7609
SUBJECT CODE	:	621
TREORY CREDITS	:	03
PRACTICAL CREDITS	:	00

**Course Objective:**

To provide foundational knowledge of Mechatronic systems, including sensors, actuators, microcontrollers, and control logic.

To develop skills in system design using hydraulic, pneumatic, and electrical components.

To enable understanding of signal processing, data conversion, and PLC-based automation.

To integrate interdisciplinary concepts for designing efficient, intelligent control systems.

**Course Content:**

Unit	Topics and Sub-topics	Hours	Marks
<b>Unit-1 Introduction to Mechatronics</b>	Introduction to Systems with mixed disciplines. Introduction to System Concepts (System, Open Loop System, close Loop System), Mechatronics: Introduction, need and applications. Mechatronics systems and components Electronics Fundamentals Review: Basic Laws (Ohms Law, KVL, KCL) and Components (Passive components, Active Components, Diode, Transistor)	<b>6</b>	<b>14</b>
<b>Unit 2 – Elements in Mechatronics</b>	Block Diagram of Mechatronic system and functions of each element: <ul style="list-style-type: none"><li>• Data conversion devices,</li><li>• sensors</li><li>• micro-sensors</li><li>• Transducers</li><li>• signal processing devices</li><li>• Timers</li><li>• Microprocessors</li><li>• Microcontrollers</li></ul> PID Controllers: Concept of Proportional, Integral, Derivative control its types and applications PLCs Hardware, types, I/O modules.	<b>9</b>	<b>14</b>
<b>Unit 3- Drives</b>	Drives: Introduction, Functions and types of drives in mechatronics. Electrical Drives: Working principal of Stepper Motors Drive, Servo Drives.	<b>10</b>	<b>14</b>

	<p>Key Features and Application of:</p> <ul style="list-style-type: none"> <li>Linear Motion bearings (ball-type, roller-type),</li> <li>cams (spherical, cylindrical and wedge cams)</li> <li>Electronic cams.</li> </ul> <p>Systems controlled by camshafts (open and close valves).</p>		
<b>Unit 4- Hydraulic System</b>	<p>Hydraulic Systems: Basic principles and Block Diagram.</p> <p>Key Components of Hydraulic System (Principle and function):</p> <ul style="list-style-type: none"> <li>Pumps: Piston Pumps, Gear Pumps, Vane Pumps.</li> <li>Flow Control Valves (Throttle Valves, Needle Valves),</li> <li>Pressure Control Valves (Pressure Relief Valves, Pressure Reducing Valves)</li> <li>Direction Control Valves Spool Type DCVs (2/2, 3/2 configurations)</li> <li>Actuators: Linear Actuators, Rotary Actuators.</li> <li>Supporting Elements: Hydraulic Reservoirs, Filters.</li> </ul> <p>Hydraulic Power Packs: Introduction and Application.</p> <p>Symbolic Representation of Hydraulic Circuit.</p>	<b>10</b>	<b>14</b>
<b>Unit-V Pneumatic System</b>	<p>Pneumatic System: Basic principles and Block Diagram.</p> <p>Production of compressed air (Principle and function):</p> <ul style="list-style-type: none"> <li>Static Compressor: Reciprocating Compressors (single-stage, two-stage), Rotary Compressors (Rotary vane compressors)</li> <li>Dynamic Compressor: Centrifugal Compressors.</li> </ul> <p>Distribution of compressed air:</p> <ul style="list-style-type: none"> <li>Selection of Pipe material and dimension, Introduction and use of Control valves.</li> </ul> <p>Conditioning of compressed air:</p> <ul style="list-style-type: none"> <li>Functions of Filter, Dryer, Lubricator.</li> </ul> <p>Pneumatic Actuators (Principle and Function):</p> <ul style="list-style-type: none"> <li>Linear actuators (Single acting and double acting cylinder),</li> <li>Rotary Actuator (Vane type)</li> </ul> <p>Graphical representations of pneumatic circuit:</p> <ul style="list-style-type: none"> <li>Symbols used for actuator, reservoir, valves, compressors, filters.</li> </ul>	<b>10</b>	<b>14</b>

#### SUGGESTED LEARNING RESOURCES:

S.No.	Title of Book	Author	Publication
1.	Analysis and design of Dynamic Systems	Cochin, Era and Cadwallender	AddisonWesley, 1997
2.	Mechatronics Engineering	Tomkinson, D. And Horne, J. Longman	McGraw Hill, 1996
3.	Mechatronics	Bolton, W	Pearson
4.	Fundamental of mecha- tronic	M. Jouaneh	Cengage Learning ISBN – 978-1111569020
5.	Mechatronics – An Integrated Approach	Clarence W. de Silva	CRC Press ISBN – 978-0849312748



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**RAJIV GANDHI PROUDYOGIKI VISHWAVIDYALAYA, BHOPAL**

**DIPLOMA IN ELECTRONICS & TELECOMMUNICATION ENGINEERING (E03)**

***SEMESTER VI***

<b>COURSE TITLE</b>	<b>:</b>	<b>INDUSTRIAL ROBOTS</b>
<b>PAPER CODE</b>	<b>:</b>	<b>7611</b>
<b>SUBJECT CODE</b>	<b>:</b>	<b>622</b>
<b>TIME DURATION FOR THEORY CLASS</b>	<b>:</b>	<b>45 Hrs.</b>

**Course Objective:** To introduce diploma students to the fundamentals of industrial robotics, providing practical knowledge of robot components, programming, and applications in manufacturing environments.

**COURSE CONTENT:**

<b>Unit</b>	<b>Topics and Sub-Topics</b>	<b>Duration</b>	<b>Marks</b>
<b>UNIT 1 - FUNDAMENTALS OF ROBOTICS</b>	<b>1.1 Introduction to Automation and Robotics</b> <ul style="list-style-type: none"><li>• Basic concepts and terminology</li><li>• Historical development of robotics</li><li>• Current and future applications</li><li>• Benefits and limitations of industrial robots</li></ul> <b>1.2 Components of Industrial Robotics</b> <ul style="list-style-type: none"><li>• Types of robot arms and configurations</li><li>• Robot architecture fundamentals</li><li>• Degrees of freedom concepts</li></ul> <b>1.3 End Effectors</b> <ul style="list-style-type: none"><li>• Types and selection criteria</li><li>• Requirements and challenges</li></ul> <b>1.4 Precision of Movement</b> <ul style="list-style-type: none"><li>• Resolution, accuracy, and repeatability concepts</li><li>• Speed and load capacity considerations</li></ul>	<b>09 hrs.</b>	<b>14</b>
<b>UNIT 2 – ROBOT KINEMATICS</b>	<b>2.1 Motion Analysis</b> <ul style="list-style-type: none"><li>• Basic rotation matrices (essential concepts only)</li><li>• Equivalent axis and angle representations</li><li>• Euler angle's introduction</li></ul> <b>2.2 Homogeneous Transformations</b> <ul style="list-style-type: none"><li>• Basic principles and applications</li></ul> <b>2.3 Manipulator Kinematics</b> <ul style="list-style-type: none"><li>• D-H notation fundamentals</li><li>• Transformation matrix basics</li><li>• Coordinate systems in robotics</li></ul> <b>2.4 Industrial Robot Kinematics</b>	<b>09 hrs.</b>	<b>14</b>

	<ul style="list-style-type: none"> <li>• Forward kinematics concepts</li> <li>• Inverse kinematics basics</li> <li>• Simple applications</li> </ul>		
<b>UNIT 3 – DYNAMICS AND TRAJECTORY PLANNING</b>	<b>3.1 Differential Transformation</b> <ul style="list-style-type: none"> <li>• Basic concepts of differential transformation</li> <li>• Introduction to Jacobians</li> </ul> <b>3.2 Robot Dynamics</b> <ul style="list-style-type: none"> <li>• Basic principles of Lagrange-Euler and Newton-Euler approaches</li> </ul> <b>3.3 Trajectory Planning</b> <ul style="list-style-type: none"> <li>• Path planning basics</li> <li>• Obstacle avoidance fundamentals</li> <li>• Motion types and planning methods</li> </ul>	<b>09 hrs.</b>	<b>14</b>
<b>UNIT 4 - ROBOT COMPONENTS &amp; SENSORS</b>	<b>4.1 Robot Actuators</b> <ul style="list-style-type: none"> <li>• Working principles of pneumatic, hydraulic, and electric actuators</li> <li>• Selection criteria and comparison</li> </ul> <b>4.2 Feedback Components</b> <ul style="list-style-type: none"> <li>• Position sensors: types and applications</li> <li>• Motion and position measurement devices</li> </ul> <b>4.3 Additional Sensors</b> <ul style="list-style-type: none"> <li>• Tactile, range, force and torque sensors</li> <li>• Selection and application</li> </ul> <b>4.4 End Effectors and Tools</b> <ul style="list-style-type: none"> <li>• Gripper types and selection</li> <li>• Specialized tools for manufacturing</li> </ul>	<b>09 hrs.</b>	<b>14</b>
<b>UNIT 5 – INDUSTRIAL ROBOT APPLICATIONS</b>	<b>5.1 Robot Applications in Manufacturing</b> <ul style="list-style-type: none"> <li>• Material transfer systems</li> <li>• Loading/unloading operation</li> </ul> <b>5.2 Manufacturing Operations</b> <ul style="list-style-type: none"> <li>• Welding, painting, and assembly applications</li> <li>• Process requirements and robot selection</li> </ul> <b>5.3 Robot Integration</b> <ul style="list-style-type: none"> <li>• Cell design fundamentals</li> <li>• Safety considerations</li> <li>• Economic justification basics</li> </ul>	<b>09 hrs.</b>	<b>14</b>

**Suggested Text Books/References:**

1. Groover, M.P. et al., "Industrial Robotics: Technology, Programming, and Applications," McGraw-Hill (Focus on chapters 1-7)
2. Craig, J.J., "Introduction to Robotics: Mechanics and Control," Pearson Education (Reference chapters 2-5 for simplified kinematics)
3. Deb, S.R., "Robotics Technology and Flexible Automation," Tata McGraw-Hill (Particularly useful for practical applications)
4. Niku, S.B., "Introduction to Robotics: Analysis, Control, Applications," Wiley (Good for simplified explanations)



## DIPLOMA WING

### RAJIV GANDHI PROUDYOGIKI VISHWAVIDYALAYA, BHOPAL

DIPLOMA IN ELECTRONICS AND TELECOMMUNICATION ENGINEERING(E03)/

DIPLOMA IN ELECTRONICS ENGINEERING(E06)

*SEMESTER VI*

COURSE TITLE	:	INDIAN CONSTITUTION
PAPER CODE	:	--
SUBJECT CODE	:	--
THEORY CREDITS	:	00
PRACTICAL CREDITS	:	00

#### Course Content

##### Unit1–The Constitution-Introduction

- The History of the Making of the Indian Constitution
- Preamble and the Basic Structure, and its interpretation
- Fundamental Rights and Duties and their interpretation
- State Policy Principles

##### Unit2–Union Government

- Structure of the Indian Union
- President–Role and Power
- Prime Minister and Council of Ministers
- Lok Sabha and Rajya Sabha

##### Unit3–State Government

- Governor–Role and Power
- Chief Minister and Council of Ministers
- State Secretariat

##### Unit4–Local Administration

- District Administration
- Municipal Corporation
- Zila Panchayat

##### Unit5–Election Commission

- Role and Functioning
- Chief Election Commissioner
- State Election Commission

**Suggested Learning Resources:**

S.No.	Title of Book	Author	Publication
1.	Ethics and Politics of the Indian Constitution	Rajeev Bhargava	Oxford University Press, New Delhi, 2008
2.	The Constitution of India	B.L. Fadia	Sahitya Bhawan; New edition (2017)
3.	Introduction to the Constitution of India	D D Basu	Lexis Nexis; Twenty-Third 2018 edition

**Suggested Software/Learning Websites:**

- a. <https://www.constitution.org/cons/india/const.html>
- b. <http://www.legislative.gov.in/constitution-of-india>
- c. <https://www.sci.gov.in/constitution>
- d. <https://www.toppr.com/guides/civics/the-indian-constitution/the-constitution-of-india/>

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DIPLOMA IN ELECTRONICS AND TELECOMMUNICATION ENGINEERING (E03)/

DIPLOMA IN ELECTRONICS ENGINEERING (E06)

SEMESTER-VI

COURSE TITLE	:	MAJOR PROJECT
PAPER CODE	:	--
COURSE CODE	:	--
THEORY CREDITS	:	00
PRACTICAL CREDITS	:	04(03+01 Credit of the V Sem.)

### MAJOR PROJECT

It should be based on real/live problems of the Industry/Govt./NGO/MSME/Rural Sector or

An innovative idea having the potential of a Startup.

Evaluation is based on work done, quality of report, performance in viva voce, presentation etc

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## **DIPLOMA WING**

**RAJIV GANDHI PROUDYOGIKI VISHWAVIDYALAYA, BHOPAL**

**DIPLOMA IN ELECTRONICS AND TELECOMMUNICATION ENGINEERING (E03)/**

**DIPLOMA IN ELECTRONICS ENGINEERING (E06)**

### ***SEMESTER VI***

COURSE TITLE	:	SEMINAR
PAPER CODE	:	--
COURSE CODE	:	--
TREORY CREDITS	:	01
PRACTICAL CREDITS	:	00

#### **SEMINAR**

Evaluation is based on work done ,quality of report  
performance in Viva-voce, presentation etc .

**DIPLOMA WING**



**RAJIV GANDHI PROUDYOGIKI VISHWAVIDYALAYA, BHOPAL**

**DIPLOMA IN ET. & TELECOMMUNICATION ENGINEERING (E03)**

**SEMESTER - VI**

COURSE TITLE	:	MAJOR PROJECT
PAPER CODE	:	--
COURSE CODE	:	--
TREORY CREDITS	:	00
PRACTICAL CREDITS	:	04 (03+01 Credit of the V Sem.)

**MAJOR PROJECT**

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**DIPLOMA WING**



**RAJIV GANDHI PROUDYOGIKI VISHWAVIDYALAYA, BHOPAL**

**DIPLOMA IN ET. & TELECOMMUNICATION ENGINEERING (E03)**

**SEMESTER - VI**

COURSE TITLE	:	SEMINAR
PAPER CODE	:	--
COURSE CODE	:	--
TREORY CREDITS	:	01
PRACTICAL CREDITS	:	00

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